

## Operational Risk Analysis Overview for Operations in the Specific Category

SORA – AMC 1 to Article 11 IR (EU) 2019/947

#### Data of authorised UAS and operation Manufacturer or Type Certificate holder Model name Type of UAS configuration Conventional airplane □ Multirotor □ Hybrid / VTOL Lighter than air Other, please specify: Is the UAS tethered during the operation? □ Yes Maximum characteristic dimensions (including propellers) Maximum take-off mass Maximum operational speed Type of propulsion system □ Combustion Electric Other, please specify: □ Hybrid, specify type: Number of type certificate or design verification report (if available) Certificate of airworthiness (if available) Number of noise certificate (if available) Transport of dangerous goods Please specify reference to Operations manual (ConOps): □ Yes Type of operation □ Visual line of sight (VLOS) Extended visual line of sight (EVLOS)

□ Beyond visual line of sight (BVLOS)

### **Specific Operations Risk Analysis**

Step #1 Operations Manual (ConOps)

### Description of proposed operations including the locations

Please provide the GPS coordinates for the operational volume (flight geography and contingency volume), the ground risk buffer and the air risk buffer (if available) as a separate file using either txt; .kmz or .kml.

Give reference to the file name:

### Short description of proposed operations

1 (8)



#### Step #2 UAS intrinsic Ground Risk Class

#### Type of operational areas on the ground

(including flight geography, contingency volume and ground risk buffer)						
Controlled ground area	□ Sparsely populated area					
□ Populated area	$\Box$ Over assemblies of people					
Specify the Intrinsic Ground Risk Class						
Remarks/Reasoning for Step #2						
Step #3 Final GRC determination						
Specify the applied ground risk mitigations, if appli	cable (tick only if mitigations are applied)					
M1 Strategic mitigations for ground risk Specify th	e level of robustness					
	□ Low					
□ Medium	□ High					
M2 Effects of ground impact are reduced Specify the level of robustness						

M1 Strategic mitigations for ground risk Specify the level of robustness						
	□ Low					
🗆 Medium	□ High					
M2 Effects of ground impact are reduced Specify	the level of robustness					
	□ Low					
🗆 Medium	🗆 High					
M3 An emergency response plan (ERP) is in place, the UAS operator is validated and effective Specify the level of robustness						
	□ Low					
🗆 Medium	🗆 High					
Specify the Final Ground Risk Class						
Remarks/Reasoning for Step #3						

#### Step #4 Initial Air Risk Class

#### Classification of the airspace where the operation is intended to be conducted

	possible)					•		
$\Box$ A	□ B	$\Box$ C	$\Box$ D	□ E	□ F	□G		
Restricte	d area (ED-F	R)		🗆 Danger area (ED-D)				
□ TMZ		□ RMZ		🗆 ATZ				
Specify the (refer to Figure 4 c	Specify the Initial Air Risk Class and the reasoning for choosing it							
ARC-a ARC-b ARC-c ARC-d						□ ARC-d		
Remarks/Reasoning for Step #4								



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Step #5 Strategic air risk mitigations and final Air Risk Class

#### Specify, if strategic mitigations of the Air Risk Class were applied

□ Yes	□ No						
Residual Air Risk Class (after strategic mitigation)							
□ ARC-a		🗆 ARC-b	□ ARC-c	□ ARC-d			
Remarks/Reasoning for Step #5							
Stop #6 TM	IPP and robu	stness level					

#### Step #6 TMPR and robustness level

#### **Tactical Mitigations Performance Requirements**

(refer to Annex D t	O AIVIC 1 to Article	12 of IR (EU) 2019/947)		
		□ No requirement (ARC-a)	□ Low (ARC-b)	□ High (ARC-d)
Remarks/Reasoning	ng for Step #6			

#### Step #7 SAIL determination

Specific Assurance and Integrity Level						
🗆 SAIL I	□ SAIL II	$\Box$ SAIL III	□ SAIL IV	$\Box$ SAIL V		

#### Step #8 SAIL Identification of Operational Safety Objectives

#### **Operational Safety Objectives**

As	per identified SAIL	from Step #7	and 2.5.2 of	AMC1 to Article 11	(Table 6	) of RG (E	U) 2019/947
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#### Step #9 Adjacent area / airspace considerations

#### Safety requirement for containment

(if one of the checkboxes is ticked, enhanced containment measures apply)	
Please specify the adjacent areas:	
$\Box$ contain assemblies of people	□ are ARC-d
If the operational volume is in a populated area:	
□ M1 mitigation was applied	$\Box$ The operating area is controlled ground area
Remarks/Reasoning for Step #9	

#### Step #10 Comprehensive safety portfolio

#### Compliance matrix for safety requirements

Please completely	fill in the compliance	e matrix for SORA Step #10 that can be found on the next page.
Have all safety req	uirements been des	cribed and met?
□ Yes	□ No	
Signature		
Date		Place
Printed name		
Signature		



#### Step #10 Comprehensive Safety Portfolio

#### Ground risk mitigations

Mitigation	Level of robustness				Remarks (e.g. EASA design verification)	Reference to documentation		
						Document name	Page number	Chapter number
M1 Strategic mitigation for ground risk	□ None	□ Low	□ Medium	🗆 High				
M1 Tethered operation (fill in only if tethered operation)	□ None	□ Low	Medium	🗆 High				
M2 Effects of ground impact are reduced (e.g. parachute)	□ None	□ Low	□ Medium	🗆 High				
M3 An emergency response plan (ERP) is in place, the UAS operator is validated and effective	□ None	□ Low	□ Medium	🗆 High				

#### Strategic air risk mitigations

Mitigation	ARC reduction	Remarks (e.g. EASA design verification)	Reference to	o document	ation
			Document name	Page number	Chapter number
Air Risk Class mitigation	□ ARC-d (AEC 1 or 2) □ ARC-c				
	□ ARC-d (AEC 1 or 2) □ ARC-b				
	□ ARC-d (AEC 3) □ ARC-c				
	□ ARC-d (AEC 3) □ ARC-b				
	□ ARC-c (AEC 4) □ ARC-b				
	□ ARC-c (AEC 5) □ ARC-b				
	□ ARC-c (AEC 6,7,8) □ ARC-b				
	🗆 ARC-c (AEC 9) 🗆 ARC-b				



	TMPR Remarks (e.g. EASA design verification) Reference				to documentation	
			Document name	Page number	Chapter number	
I MPR-level						
	□ No requirement (ARC-a)					
	□ Low requirement (ARC-b)					
	Medium requirement (ARC-c)					
	□ High requirement (ARC-d)					
	Detect					
	Decide					
TMPR-function	Command					
	Execute					
	Feedback loop					
TMPR-robustness	TMPR integrity and assurance objectives					

#### Adjacent area/airspace considerations

	Level of containment	Remarks (e.g. EASA design verification)	Reference to	o document	ation
			Document name	Page number	Chapter number
Safety requirement	🗆 Basic containment 🗆 Enhanced containment				



**Operational Safety Objectives** 

	Level of containment				Remarks (e.g. EASA design verification)	Reference to documentation		
OSO #01 Ensure that the						Document name	Page number	Chapter number
UAS operator is competent and/or proven	☐ Optional	⊔ Low		⊔ High				
OSO #02 UAS								
competent and/or proven entity	□ Optional	□ Low	🗆 Medium	🗆 High				
OSO #03 UAS								
maintained by competent and/or proven entity		∟ Low		⊔ Hign				
OSO #04 UAS								
developed to authority	Optional	$\Box$ Low	🗆 Medium	🗆 High				
standards								
OSO #05 UAS is								
designed considering	Optional	$\Box$ Low	🗆 Medium	🗆 High				
reliability								
OSO #06 C3 link								
characteristics are	Optional	□ Low	□ Medium	🗆 High				
operation								
OSO #07 Inspection of								
the UAS (product inspec-			🗆 Medium	🗆 Hiab				
consistency with the								
Co-nOps								
OSO #08 Operational								
procedures are defined,		□ Low	🗆 Medium	🗆 High				
Validated and adhered to								
USU #U9 Remote crew								
able to control the		$\Box$ Low	🗆 Medium	🗆 High				
abnormal situation								



	Level of containment			Remarks (e.g. EASA design verification)	Reference to documentation		
		1			Document name	Page number	Chapter number
OSO #10 Safe recovery	□ Low	□ Medium	🗆 Hiah				
from a technical issue							
OSO #11 Procedures							
are in-place to handle							
the deterioration of	L Low	∐ Medium	⊔ High				
external systems sup-							
porting UAS operations							
OSO #12 The UAS is							
designed to manage the							
de-terioration of external	Low		🗆 High				
systems support-ing							
UAS operations							
OSO #13 External							
services supporting UAS	🗆 Low	□ Medium	🗆 High				
opera-tions are adequate			0				
101 the operation							
050 #14 Operational							
procedures are defined,							
OSO #15 Pomoto grow							
trained and current and							
able to control the	🗆 Low	🗆 Medium	🗆 High				
able to control the							
OSO #16 Multi-crew							
coordination	🗆 Low	🗆 Medium	🗆 High				
OSO #17 Remote crew							
is fit to operate							
OSO #18 Automatic							
protection of the flight		□ Modium					
enve-lope from human							
error							
OSO #19 Safe recovery		🗆 Medium					
from human error							



	Level of containment				Remarks (e.g. EASA design verification)	Reference to documentation		
OSO #20 A human factors evaluation has been performed and the human machine interface (HMI) found appropriate for the mission	□ Optional	□ Low	□ Medium	🗆 High		Document name	Page number	Chapter number
OSO #21 Operational procedures are defined, validated and adhered to		□ Low	□ Medium	🗆 High				
OSO #22 The remote crew is trained to identify critical environmental conditions and to avoid them		□ Low	□ Medium	🗆 High				
OSO #23 Environmental conditions for safe oper- ations are defined, measurable and ad- hered to		□ Low	□ Medium	🗆 High				
OSO #24 UAS is designed and qualified for ad-verse environmental conditions	□ Optional	□ Low	□ Medium	🗆 High				

Signature

Date	Place
Drinted name	
Printed name	
Signature	
-	